Robotics Service Bus - Tasks #1014
Make Spread conditionally dependant in Python RSB implementation

06/21/2012 03:33 PM - S. Wrede

Status:	Resolved		**Start date:**	06/21/2012
Priority:	Normal		**Due date:**	
Assignee:	J. Wienke		**% Done:**	100%
Category:	Python		**Estimated time:**	0.00 hour
Target version:	rsb-0.7			

Description

RSB Python should no longer depend on Python by default. Relevant to distribute RSB without Python.

Associated revisions

Revision 5f743a52 - 06/22/2012 03:16 PM - J. Wienke

- make it possible to instantiate the inprocess transport
- make socket the default transport
- make spread optional, fixes #1014
- fix a bug where an unknown OutConnector was used when creating a socket connector
- port all unit tests to use the local transport as a default

History

#1 - 06/21/2012 06:34 PM - J. Wienke

- Status changed from New to In Progress

#2 - 06/22/2012 03:20 PM - J. Wienke

- Status changed from In Progress to Resolved

- % Done changed from 0 to 100

Applied in changeset r3616.