# Packaging - Tasks #1019 PyPi entry for rsb-python

06/22/2012 04:32 PM - J. Moringen

Status: Start date: Resolved 06/22/2012

**Priority:** Normal Due date:

Assignee: J. Moringen % Done: 100%

Category:

**Estimated time:** 0.00 hour Target version: rsb-0.7

**Description** 

Related issues:

Related to Packaging - Tasks # 1004: Create Debian packages for rsb-python, r... New 06/18/2012

Blocked by Robotics Service Bus - Tasks # 926: Release version 0.7 Resolved

## History

### #1 - 06/22/2012 06:25 PM - J. Wienke

- % Done changed from 0 to 20

Initially registered

### #2 - 06/22/2012 07:03 PM - J. Wienke

- % Done changed from 20 to 30

I have modified the setup to be more consistent with pypi conventions. Additionally an automatic job is missing to push releases there. The first release is uploaded manually by me.

#### #3 - 06/25/2012 04:55 PM - J. Wienke

- Assignee changed from J. Wienke to J. Moringen
- % Done changed from 30 to 90

A job on the CI server is now available (https://ci.cor-lab.org/job/rsb-python-0.7-pypi/). It is disabled right now and needs to be reenabled once the 0.7 branch exists pointing to that branch and with a fixed trigger for rsb-protocol-0.7 then.

## #4 - 08/11/2012 05:36 AM - J. Moringen

- Status changed from In Progress to Resolved
- % Done changed from 90 to 100

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