

Robotics Service Bus - Tasks #1059

Feature # 713 (Resolved): Implement socket-based transport

Implement bus connection functionality

07/06/2012 02:53 PM - J. Moringen

Status:	Resolved	Start date:	07/06/2012
Priority:	Immediate	Due date:	
Assignee:	J. Wienke	% Done:	100%
Category:	Java	Estimated time:	0.00 hour
Target version:	rsb-0.9		
Description			
<ul style="list-style-type: none">- Client functionality is implemented- Server functionality is TODO- Integration into transport infrastructure will be done later			

Associated revisions

Revision e9f5d7dc - 07/18/2013 01:51 PM - J. Wienke

fixes #1059: Finalized bus connection structures.

Merge branch 'task-1059'

History

#1 - 07/20/2012 10:06 PM - J. Moringen

- Target version changed from rsb-0.7 to rsb-0.9

#2 - 07/16/2013 11:32 PM - J. Wienke

- Assignee changed from S. Wrede to J. Wienke

#3 - 07/19/2013 12:43 AM - J. Wienke

- Status changed from In Progress to Resolved

- % Done changed from 50 to 100

Applied in changeset rsb-java|commit:e9f5d7dc57dfd32668fd95e091f98e0b1231249d.