

Robotics Service Bus - Tasks #1059

Feature # 713 (Resolved): Implement socket-based transport

Implement bus connection functionality

07/06/2012 02:53 PM - J. Moringen

<b>Status:</b>	Resolved	<b>Start date:</b>	07/06/2012
<b>Priority:</b>	Immediate	<b>Due date:</b>	
<b>Assignee:</b>	J. Wienke	<b>% Done:</b>	100%
<b>Category:</b>	Java	<b>Estimated time:</b>	0.00 hour
<b>Target version:</b>	rsb-0.9		
<b>Description</b> <ul style="list-style-type: none"><li>- Client functionality is implemented</li><li>- Server functionality is TODO</li><li>- Integration into transport infrastructure will be done later</li></ul>			

Associated revisions

Revision e9f5d7dc - 07/18/2013 01:51 PM - J. Wienke

fixes #1059: Finalized bus connection structures.

Merge branch 'task-1059'

History

#1 - 07/20/2012 10:06 PM - J. Moringen

- Target version changed from rsb-0.7 to rsb-0.9

#2 - 07/16/2013 11:32 PM - J. Wienke

- Assignee changed from S. Wrede to J. Wienke

#3 - 07/19/2013 12:43 AM - J. Wienke

- Status changed from In Progress to Resolved

- % Done changed from 50 to 100

Applied in changeset rsb-java|commit:e9f5d7dc57dfd32668fd95e091f98e0b1231249d.