

## Robotics Service Bus - Enhancement #1096

### QueuePushHandler should not pollute main namespace of RSB

07/24/2012 01:17 PM - J. Wienke

Status:	Resolved	Start date:	07/24/2012
Priority:	Normal	Due date:	
Assignee:	J. Wienke	% Done:	100%
Category:	C++	Estimated time:	0.00 hour
Target version:	rsb-0.10		

**Description**

Currently the queue push handler resides in the top-level namespace of RSB, which looks kind of awkward to me as it is a utility class, which is not necessary for RSB to function properly. I would vote to move it to a util namespace or something like that. If we don't do it now, the API break will get even worse later if more of these special handlers are there.

### History

#1 - 07/24/2012 01:20 PM - J. Wienke

This also includes EventQueuePushHandler

#2 - 12/20/2012 05:08 PM - J. Moringen

- Target version changed from rsb-0.9 to rsb-0.10

#3 - 09/03/2013 10:04 AM - J. Wienke

- Status changed from New to In Progress

- Assignee set to J. Wienke

#4 - 09/03/2013 03:49 PM - J. Wienke

- Status changed from In Progress to Resolved

- % Done changed from 0 to 100

Implemented in commit:rsb-cpp|53b9a870

#5 - 09/03/2013 03:54 PM - J. Moringen

Since this constitutes an incompatible API change, can you add it to the section for version 0.10 in news.rst in the manual?

#6 - 09/03/2013 04:52 PM - J. Wienke

Backwards compatibility is so far maintained with a deprecation warning. Do you think this is necessary then?

#7 - 09/09/2013 03:53 PM - J. Moringen

Maybe a note could be added so people can start to migrate?

#8 - 09/09/2013 05:01 PM - J. Wienke

A deprecation compiler warning is issues in case you are using the old includes. I think we discussed that this is enough so far.