Robotics Service Bus - Tasks #1105
allow selection of strategies on command line

07/30/2012 03:01 PM - J. Wienke

Status:	Resolved	**Start date:**	10/06/2011
Priority:	Low	**Due date:**	
Assignee:	J. Wienke	**% Done:**	0%
Category:	C++ Tools	**Estimated time:**	0.00 hour
Target version:			

Description

History

#1 - 07/30/2012 03:01 PM - J. Wienke

Moved from old timesync project to be part of the overall rsb project. timesync seems to be quite essential for some use cases with RSB. Hence we moved it to the main project as a tool.