

Robotics Service Bus - Tasks #1107

create strategy for itd sync

07/30/2012 03:01 PM - J. Wienke

Status:	Resolved	Start date:	10/06/2011
Priority:	Normal	Due date:	
Assignee:	J. Wienke	% Done:	100%
Category:	C++ Tools	Estimated time:	0.00 hour
Target version:			
Description			
1:n with time interval			
<ul style="list-style-type: none">- requires short buffer- first iteration could assume that events are received without latency and jitter and in sync for both channels			

History

#1 - 07/30/2012 03:01 PM - J. Wienke

Moved from old timesync project to be part of the overall rsb project. timesync seems to be quite essential for some use cases with RSB. Hence we moved it to the main project as a tool.