Robotics Service Bus - Tasks #1107
create strategy for itd sync

07/30/2012 03:01 PM - J. Wienke

Status:	Resolved	**Start date:**	10/06/2011
Priority:	Normal	**Due date:**	
Assignee:	J. Wienke	**% Done:**	100%
Category:	C++ Tools	**Estimated time:**	0.00 hour
Target version:			

Description

1:n with time interval

- requires short buffer
- first iteration could assume that events are received without latency and jitter and in sync for both channels

History

#1 - 07/30/2012 03:01 PM - J. Wienke

Moved from old timesync project to be part of the overall rsb project. timesync seems to be quite essential for some use cases with RSB. Hence we moved it to the main project as a tool.