Robotics Service Bus - Tasks #1108 allow to specify strategy-specific options

07/30/2012 03:01 PM - J. Wienke

Status: Resolved Start date: 10/06/2011 **Priority:** Low Due date: Assignee: % Done: 100% Category: C++ Tools **Estimated time:** 0.00 hour Target version: Description how do properties for factory help?

History

#1 - 07/30/2012 03:01 PM - J. Wienke

Moved from old timesync project to be part of the overall rsb project. timesync seems to be quite essential for some use cases with RSB. Hence we moved it to the main project as a tool.

05/03/2024 1/1