Robotics Service Bus - Tasks #1110
Split runner app and other code

07/30/2012 03:01 PM - J. Wienke

Status:	Resolved		**Start date:**	10/20/2011
Priority:	Normal		**Due date:**	
Assignee:			**% Done:**	100%
Category:	C++ Tools		**Estimated time:**	0.00 hour
Target version:				

Description

A library + a console front-end are better for deployment of the strategies, also in-process.

History

#1 - 07/30/2012 03:01 PM - J. Wienke

Moved from old timesync project to be part of the overall rsb project. timesync seems to be quite essential for some use cases with RSB. Hence we moved it to the main project as a tool.