

Robotics Service Bus - Tasks #1111

Push general event serialization solution to RSB core

07/30/2012 03:01 PM - J. Wienke

Status:	Resolved	Start date:	10/20/2011
Priority:	Normal	Due date:	
Assignee:	J. Wienke	% Done:	100%
Category:	C++ Tools	Estimated time:	0.00 hour
Target version:			

Description

This includes:

- converter: otherwise clients always need to link against the sync library even if the sync itself is running in another process
- protocol for event serialization: this is also required for rsbbag. (jan?)

History

#1 - 07/30/2012 03:01 PM - J. Wienke

Moved from old timesync project to be part of the overall rsb project. timesync seems to be quite essential for some use cases with RSB. Hence we moved it to the main project as a tool.