

Robotics Service Bus - Tasks #1113

Make timestamp for synchronizing configurable

07/30/2012 03:01 PM - J. Wienke

Status:	Resolved	Start date:	11/07/2011
Priority:	Normal	Due date:	
Assignee:		% Done:	100%
Category:	C++ Tools	Estimated time:	2.00 hours
Target version:			
Description			
<p>This is required as there seems to be no reasonable default. Out must also be possible to specify timestamps provided by the user. Maybe a priority list is the best way to handle this because use times might not be available on every event.</p>			

History

#1 - 07/30/2012 03:01 PM - J. Wienke

Moved from old timesync project to be part of the overall rsb project. timesync seems to be quite essential for some use cases with RSB. Hence we moved it to the main project as a tool.