

## Robotics Service Bus - Tasks #1115

### Make rsbtimesync compile and run with rsb 0.5

07/30/2012 03:01 PM - J. Wienke

<b>Status:</b>	Resolved	<b>Start date:</b>	11/29/2011
<b>Priority:</b>	Urgent	<b>Due date:</b>	
<b>Assignee:</b>	J. Wienke	<b>% Done:</b>	100%
<b>Category:</b>	C++ Tools	<b>Estimated time:</b>	0.00 hour
<b>Target version:</b>			
<b>Description</b>			

#### History

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#1 - 07/30/2012 03:01 PM - J. Wienke

Moved from old timesync project to be part of the overall rsb project. timesync seems to be quite essential for some use cases with RSB. Hence we moved it to the main project as a tool.