

Robotics Service Bus - Enhancement #1123

Improve documentation for debian package installation wrt spread transport

08/03/2012 12:43 PM - C. Emmerich

Status: New	Start date: 08/03/2012
Priority: Normal	Due date:
Assignee:	% Done: 0%
Category:	Estimated time: 0.00 hour
Target version:	
Description	
After installing rsb0.7 and rsbcptools0.7 with debian packages, rsb throws a runtime error: terminate called after throwing an instance of 'rsc::patterns::NoSuchImpl' what(): no implementation of interface `rsb::transport::InPushConnector' found for specified key `spread' Aborted	
Note: I do not remember this issue occurring when I installed rsb0.7 manually...	
Related issues:	
Related to Robotics Service Bus - Bug # 1124: Debian package rsb-tools-cpp0.7...	Closed 08/03/2012

History

#1 - 08/03/2012 12:48 PM - J. Wienke

You need to install rsb-spread, otherwise you end up with an rsb version without spread support.

#2 - 08/03/2012 12:53 PM - Anonymous

Seems to be correct, that the rsb package doesn't include the spread transport.

However:

1. rsb-spread package is missing on the server right now,. this is probably just a temporary issue due to package server resetting
2. rsb0.7 troubleshooting docs should point to the rsb-spread package as solution for Problem 1 (*spread doesn't work anymore*)
3. The raised exception could be clearer, for example saying that *rsb is built without spread*

#3 - 08/03/2012 12:56 PM - J. Wienke

- Tracker changed from Bug to Enhancement

- Subject changed from *RSB0.7 debian package seems to be misconfigured to Improve documentation for debian package installation wrt spread transport*

- Priority changed from Urgent to Normal

For the package server there actually is a file in the pool. So the index must be broken.

Please open up a second issue for the package server thing.