# Robotics Service Bus - Enhancement #1123 Improve documentation for debian package installation wrt spread transport

08/03/2012 12:43 PM - C. Emmerich

Status:	New	Start date:	08/03/2012
Priority:	Normal	Due date:	
Assignee:		% Done:	0%
Category:		Estimated time:	0.00 hour
Target version:			

## **Description**

After installing rsb0.7 and rsbcpptools0.7 with debian packages, rsb throws a runtime error:

terminate called after throwing an instance of 'rsc::patterns::NoSuchImpl'

what(): no implementation of interface `rsb::transport::InPushConnector' found for specified key `spread'

Aborted

Note: I do not remember this issue occuring when I installed rsb0.7 manually...

## Related issues:

Related to Robotics Service Bus - Bug # 1124: Debian package rsb-tools-cpp0.7... Closed 08/03/2012

## History

## #1 - 08/03/2012 12:48 PM - J. Wienke

You need to install rsb-spread, otherwise you end up with an rsb version without spread support.

## #2 - 08/03/2012 12:53 PM - Anonymous

Seems to be correct, that the rsb package doesn't include the spread transport.

#### However:

- 1. rsb-spread package is missing on the server right now,. this is probably just a temporary issue due to package server resetting
- 2. rsb0.7 troubleshooting docs should point to the rsb-spread package as solution for Problem 1 (spread doesn't work anymore)
- 3. The raised exception could be clearer, for example saying that rsb is built without spread

## #3 - 08/03/2012 12:56 PM - J. Wienke

- Tracker changed from Bug to Enhancement
- Subject changed from RSB0.7 debian package seems to be misconfigured to Improve documentation for debian package installation wrt spread transport
- Priority changed from Urgent to Normal

For the package server there actually is a file in the pool. So the index must be broken.

Please open up a second issue for the package server thing.

03/13/2024 1/1