

Robotics Service Bus - Enhancement #1126

Make multiple RSB C++ versions installable in parallel

08/03/2012 03:16 PM - J. Moringen

Status:	Resolved	Start date:	08/03/2012
Priority:	Normal	Due date:	
Assignee:	J. Moringen	% Done:	100%
Category:	C++	Estimated time:	0.00 hour
Target version:	rsb-0.9		
Description			
Since the shared objects are already versioned, this should be achievable by installing headers into versioned directories. E.g. /usr/include/rsb-0.8.			

Associated revisions

Revision 26c739b3 - 08/31/2012 12:59 AM - J. Moringen

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fixes #1126

- RSBConfig.cmake.in: changed RSB_INCLUDE_DIRS to include INSTALL_PATH_PREFIX; depend on specific version of RSC
- rsb.pc.in: changed includedir to include INSTALL_PATH_PREFIX; depend on specific version of RSC library; specify versioned RSB library
- CMakeLists.txt: added INSTALL_PATH_PREFIX; install pkg-config module into versioned path; install CMake module into versioned path; install license file into versioned path
- src/CMakeLists.txt: do not install unversioned symlink for library; install headers into versioned path

History

#1 - 08/31/2012 12:51 AM - J. Moringen

- Status changed from New to In Progress
- Assignee set to J. Moringen

#2 - 08/31/2012 05:46 AM - J. Moringen

- Status changed from In Progress to Resolved
- % Done changed from 0 to 100

Applied in changeset rsb-cpp|commit:26c739b33a7dd0a43a54ded2b0f093d01290ffcd.