

Robotics Service Bus - Feature #1134

Add CMake rules for building, testing and packaging

08/07/2012 06:04 PM - J. Moringen

Status:	Resolved	Start date:	08/07/2012
Priority:	Normal	Due date:	
Assignee:	J. Moringen	% Done:	100%
Category:	ROS Connector	Estimated time:	0.00 hour
Target version:	rsb-0.9		
Description			

Associated revisions

Revision 646b45bb - 08/07/2012 06:10 PM - J. Moringen

Added CMake build rules and Debian packaging rules

fixes #1134

- CMakeLists.txt: new file; contains CMake rules for building, testing and installing
- sbcl.cmake.in: new file; template for calling SBCL; configured by CMake
- cpack/CPackInclude.cmake: new file; helper for including CPack with some basic configuration logic
- cpack/DebianUbuntu.cmake: new file; packaging rules for Ubuntu

History

#1 - 08/07/2012 06:12 PM - J. Moringen

- *Project changed from Rosetta Stone Project to Robotics Service Bus*
- *Category changed from ROS Backend to ROS Connector*

#2 - 08/07/2012 06:12 PM - Anonymous

- *Status changed from New to Resolved*
- *% Done changed from 0 to 100*

Applied in changeset rsb-ros-cl|commit:646b45bb5ee447babb634d050a61899721571ae8.