

Robotics Systems Types - Tasks #1155

Make multiple versions of rst-converters installable in parallel

08/29/2012 05:02 PM - J. Wienke

Status:	Resolved	Start date:	08/29/2012
Priority:	Normal	Due date:	
Assignee:		% Done:	100%
Category:	Build System	Estimated time:	0.00 hour
Target version:	rsb-0.9		
Description			

History

#1 - 12/11/2012 12:07 PM - S. Herbrechtsmeier

Do you want to support the parallel usage of different rst-converters versions in a distribution?

If so please add the version to the project (library) name as it is done in other projects. This means that you have a pkg-config file and library name link per version so that you can use the linker library namespace option. The current behavior doesn't work with the PKG_CONFIG_SYSROOT_DIR option of pkg-config which is useful when cross compiling packages.

#2 - 06/05/2013 09:53 PM - J. Moringen

- Status changed from New to Resolved

- % Done changed from 0 to 100