

Robotics Service Bus - Tasks #1165

Tasks # 43 (Closed): Encapsulate Transport Implementations in Extension Libraries

Provide YARP transport as plugin (C++)

09/16/2012 03:05 PM - J. Moringen

<b>Status:</b>	Resolved	<b>Start date:</b>	09/16/2012
<b>Priority:</b>	Normal	<b>Due date:</b>	
<b>Assignee:</b>	J. Moringen	<b>% Done:</b>	100%
<b>Category:</b>	YARP Connector	<b>Estimated time:</b>	0.00 hour
<b>Target version:</b>	rsb-0.9		
<b>Description</b>			

History

#1 - 09/16/2012 03:07 PM - J. Moringen

- File 0001-Added-RSB-plugin-support-in-src-rsb-Plugin.cpp.patch added

Attached proposed patch.

#2 - 12/06/2012 10:23 PM - J. Moringen

- Status changed from Feedback to Resolved

- % Done changed from 80 to 100

The patch has been applied in the meantime.

Files

0001-Added-RSB-plugin-support-in-src-rsb-Plugin.cpp.patch	4.35 KB	09/16/2012	J. Moringen
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