

Robotics Service Bus - Tasks #1165

Tasks # 43 (Closed): Encapsulate Transport Implementations in Extension Libraries

Provide YARP transport as plugin (C++)

09/16/2012 03:05 PM - J. Moringen

Status:	Resolved	Start date:	09/16/2012
Priority:	Normal	Due date:	
Assignee:	J. Moringen	% Done:	100%
Category:	YARP Connector	Estimated time:	0.00 hour
Target version:	rsb-0.9		
Description			

History

#1 - 09/16/2012 03:07 PM - J. Moringen

- File 0001-Added-RSB-plugin-support-in-src-rsb-Plugin.cpp.patch added

Attached proposed patch.

#2 - 12/06/2012 10:23 PM - J. Moringen

- Status changed from Feedback to Resolved

- % Done changed from 80 to 100

The patch has been applied in the meantime.

Files

0001-Added-RSB-plugin-support-in-src-rsb-Plugin.cpp.patch	4.35 KB	09/16/2012	J. Moringen
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