Robotics Service Bus - Tasks #1187
Fix so_version of 0.7

10/04/2012 03:57 PM - Anonymous

Status:	Resolved		**Start date:**	10/04/2012
Priority:	High		**Due date:**	
Assignee:			**% Done:**	100%
Category:	Configuration		**Estimated time:**	0.00 hour
Target version:	rsb-0.7			

Description

The so-version of rsb libraries of the 0.7 release is still containing the patch version. This was fixed already for rsb 0.8 to just contain major and minor version, but not yet for 0.7.

The issue was reported downstream because it requires recompiling of depending software on every patch in the 0.7 version. Any objections to backport this change also to 0.7?

Associated revisions

Revision c8eaedc2 - 10/04/2012 04:11 PM - J. Moringen

Backport: Added more conservative so-version in {,src}/CMakeLists.txt

fixes #1187

- CMakeLists.txt: added variable SO_VERSION which is intended to be
  used as shared object version; set to MAJOR.MINOR to allow parallel
  installation of releases and preserve compatibility within
  individual releases
- src/CMakeLists.txt: use SO_VERSION as shared object version of the
  library

History

#1 - 10/04/2012 04:12 PM - J. Moringen

- Status changed from Feedback to Resolved

- % Done changed from 0 to 100

Applied in changeset rsb-cpp|commit:c8eaedc2080c845d72b06bf26ea8c4efe952c6f1.