Robotics Systems Types - Tasks #1195
Document workflow with new git infrastructure

10/10/2012 10:47 AM - Anonymous

Status:	Resolved		**Start date:**	10/10/2012
Priority:	High		**Due date:**	
Assignee:			**% Done:**	100%
Category:			**Estimated time:**	0.00 hour
Target version:				

Description

Since rst was moved to git, the old workflows don't seem to be working any more. Example: I can no longer just commit protos to the sandbox. If I run on the stable 0.7 release (which is default), committing protos to trunk won't have any effect on my installation. Opening the stable 0.7 release for experimental proto commits is also not really an option I think (otherwise is has to be documented). But if I instead create my own branch 0.7-foobar for own experimentation, none of the infrastructure that we advertise to our project partners (gar, debian) is working any more.

History

#1 - 10/10/2012 06:38 PM - Anonymous

- *Tracker changed from Bug to Tasks*

- *Status changed from New to In Progress*

- *Assignee changed from S. Wrede to Anonymous*

#2 - 10/10/2012 07:25 PM - Anonymous

- *Status changed from In Progress to Resolved*

- *% Done changed from 0 to 100*

Please find it at: http://docs.cor-lab.de/rst-manual/0.7/html/data-types.html