Robotics Systems Types - Tasks #1212
Add RSB plugins which register converters when loaded

10/22/2012 12:55 PM - J. Moringen

Status:	Resolved		**Start date:**	10/22/2012
Priority:	Normal		**Due date:**	
Assignee:	J. Moringen		**% Done:**	100%
Category:	cpp		**Estimated time:**	0.00 hour
Target version:	rsb-0.9			

Description

Associated revisions

Revision 34f3f28f - 10/22/2012 03:15 PM - J. Moringen

Generate RSB plugins for stable and sandbox in CMakeLists.txt

fixes #1212

- cpp/src/CMakeLists.txt: generate include and registration code for
  stable and sandbox plugins; build and install plugin libraries
- cpp/src/Plugin.cpp.in: new file; is configured twice, as plugin main
  file for stable and sandbox components which registers the
  respectively available converters

Revision 2f228b50 - 10/23/2012 03:30 AM - J. Moringen

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Revision 48153916 - 10/23/2012 03:30 AM - J. Moringen

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Revision a5aacd19 - 10/23/2012 03:30 AM - J. Moringen

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History

#1 - 10/23/2012 06:02 PM - J. Moringen

- % Done changed from 0 to 80

#2 - 10/23/2012 07:52 PM - Anonymous

- Status changed from In Progress to Resolved

- % Done changed from 80 to 100

Applied in changeset rst-converters|commit:34f3f28f4701483161684e77739840ed9c4ae043.