

Robotics Service Bus - Tasks #124

Create quality of service system

09/12/2010 11:52 PM - J. Wienke

Status:	Resolved	Start date:	09/12/2010
Priority:	Normal	Due date:	
Assignee:	J. Wienke	% Done:	0%
Category:	C++	Estimated time:	2.00 hours
Target version:			
Description			
Decide whether messages can be delivered arbitrarily or ordered delivery is required.			

Associated revisions

Revision 671a2a44 - 11/12/2010 11:55 AM - J. Wienke

Introduce a QoS object, refs #124

Revision 96fc7ba1 - 11/12/2010 05:15 PM - J. Wienke

Implement a basic QoS management for sending messages

fixes #124

History

#1 - 11/12/2010 11:37 AM - J. Wienke

- Status changed from New to In Progress
- Assignee changed from S. Wrede to J. Wienke

#2 - 11/13/2010 12:54 PM - J. Wienke

- Status changed from In Progress to Resolved