

## Robotics Service Bus - Enhancement #1247

### Remove singleton backwards compatibility for factories

11/19/2012 10:53 PM - J. Wienke

<b>Status:</b>	Resolved	<b>Start date:</b>	11/19/2012
<b>Priority:</b>	Normal	<b>Due date:</b>	
<b>Assignee:</b>		<b>% Done:</b>	100%
<b>Category:</b>	C++	<b>Estimated time:</b>	0.00 hour
<b>Target version:</b>	rsb-0.12		
<b>Description</b>			
This was introduced and marked as deprecated to force users to convert to the new api.			
<b>Related issues:</b>			
Related to Robotics Service Bus - Bug # 1245: Singleton factories do not work...			<b>Resolved</b> <b>11/19/2012</b>

#### Associated revisions

##### Revision 1f6bddf1 - 03/13/2015 06:50 PM - J. Wienke

Remove singleton usage in public API

Removes deprecated code.

fixes #1247

##### Revision c98cacac - 05/01/2015 09:34 PM - J. Moringen

Mention removed Factory::getInstance in news.rst

refs #1247

- news.rst (0.12): mention removed Factory::getInstance method in the C++ implementation

##### Revision ce0712f7 - 05/08/2015 12:17 AM - J. Moringen

Backport: Mention removed Factory::getInstance in news.rst

refs #1247

- news.rst (0.12): mention removed Factory::getInstance method in the C++ implementation

#### History

##### #1 - 12/10/2013 11:47 PM - J. Moringen

- Target version changed from rsb-0.10 to rsb-0.11

##### #2 - 02/06/2014 05:30 PM - J. Moringen

- Target version changed from rsb-0.11 to rsb-0.12

**#3 - 02/06/2014 05:32 PM - J. Moringen**

- *Target version changed from rsb-0.12 to rsb-1.0*

**#4 - 12/11/2014 07:53 PM - J. Moringen**

- *Target version changed from rsb-1.0 to rsb-0.12*

**#5 - 03/13/2015 06:29 PM - J. Wienke**

- *Status changed from New to In Progress*

**#6 - 03/13/2015 06:56 PM - J. Wienke**

- *Status changed from In Progress to Resolved*

- *% Done changed from 0 to 100*

Applied in changeset commit:rsb-cpp|1f6bddf165f9fdf04d573f766c1a84faa7f653b8.