Robotics Service Bus - Support #1298 RSB and openCV: compile success depends on order of includes

12/13/2012 11:36 AM - C. Emmerich

Related issues:

| Status: | Rejected | Start date: | 12/13/2012 |
|---|----------|-----------------|------------|
| Priority: | Normal | Due date: | |
| Assignee: | | % Done: | 0% |
| Category: | | Estimated time: | 0.00 hour |
| Target version: | | | |
| Description | | | |
| | | | |
| When including rsb-headers and openCV-headers in a project the succuess of compilation depends on the ordering of the includes. | | | |
| The following works | | | |
| #include <rsb factory.h=""></rsb> | | | |
| #include <cv.h></cv.h> | | | |
| | | | |
| int main (int argc, char **argv) { | | | |
| // stuff | | | |
| return 0; | | | |
| } | | | |
| | | | |
| | | | |
| | | | |
| whereas switching the include order to | | | |
| | | | |
| #include <cv.h></cv.h> | | | |
| #include <rsb factory.h=""></rsb> | | | |
| | | | |
| | | | |
| results in a compile error: | | | |
| results in a compile error. | | | |
| [57%] Building CXX object FlexIRobPerceptionChain/CMakeFiles/FlexIRobPerceptionChain.dir/main.cpp.o | | | |
| In file included from /vol/flexirob/releases/trunk/include/rsb/Factory.h:41, | | | |
| | | • | |
| from /homes/cemmeric/flexirob_workspace/Perception/FlexIRobPerceptionChain/main.cpp:23: | | | |
| /vol/flexirob/releases/trunk/include/rsb/ParticipantConfig.h:217: error: expected identifier before 'goto' | | | |
| /vol/flexirob/releases/trunk/include/rsb/ParticipantConfig.h:217: error: expected '}' before 'goto' | | | |
| /vol/flexirob/releases/trunk/include/rsb/ParticipantConfig.h:217: error: expected unqualified-id before 'goto' | | | |
| /vol/flexirob/releases/trunk/include/rsb/ParticipantConfig.h:224: error: expected unqualified-id before ')' token | | | |
| /vol/flexirob/releases/trunk/include/rsb/ParticipantConfig.h:225: error: declaration of '~rsb::ParticipantConfig' as non-member | | | |
| /vol/flexirob/releases/trunk/include/rsb/ParticipantConfig.h:232: error: non-member function 'rsb::QualityOfServiceSpec | | | |
| rsb::getQualityOfServiceSpec()' cannot have cv-qualifier | | | |
| /vol/flexirob/releases/trunk/include/rsb/ParticipantConfig.h:253: error: 'ErrorStrategy' does not name a type | | | |
| | | | |
| | | | |
| | | | |
| | | | |
| Is this a bug in rsb? Or in openCV? Can that be fixed somehow? | | | |
| | | | |

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History

#1 - 12/13/2012 12:23 PM - J. Moringen

This is most likely a bug in OpenCV which probably contains code along the lines

#define EXIT goto bla bla

If project:rsb header are included after this definition, the token EXIT in the project:rsb code expands to goto bla bla, which does not make sense.

This could be fixed by renaming EXIT to something in project:rsb. But where should we stop? Upstream libraries could define a macro on any name.

#2 - 12/13/2012 12:25 PM - J. Wienke

- Status changed from New to Rejected

This is actually a duplicate of #1175.

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