

RSB OpenCV [Deprecated] - Bug #1308

Display depth image from Kinect camera or other 3D sensors

12/18/2012 05:53 PM - S. Wrede

Status:	Resolved	Start date:	12/18/2012
Priority:	Normal	Due date:	
Assignee:	S. Wrede	% Done:	100%
Category:		Estimated time:	0.00 hour
Target version:	rsb-0.9		
Description			
Display's rst.vision.SimpleXYZImage types.			
Scope can be specified using the -i command line parameter.			

Associated revisions

Revision 33 - 12/18/2012 05:57 PM - S. Wrede

Added implementation for displaying rst.vision.SimpleXYZImage depth images, fixes #1308.

History

#1 - 12/18/2012 05:57 PM - S. Wrede

- Status changed from New to Resolved
- % Done changed from 0 to 100

Applied in changeset r33.