

Robotics Service Bus - Bug #1358

Example for converter registration in Python is wrong

01/25/2013 03:33 PM - J. Moringen

Status:	Resolved	Start date:	01/25/2013
Priority:	Normal	Due date:	
Assignee:	J. Moringen	% Done:	100%
Category:	Documentation	Estimated time:	0.00 hour
Target version:	rsb-0.9		
Description			

Associated revisions

Revision 671f4de5 - 01/25/2013 03:38 PM - J. Moringen

Fixed description of default global participant config in examples-converter.rst

refs #1358

- examples-converter.rst: changed description to reflect that we now use rsb.setDefaultParticipantConfig instead of setting rsb.__defaultParticipantConfig

Revision dd9e64a1 - 01/25/2013 03:40 PM - J. Moringen

Fixed manipulation of default participant config in examples/protobuf/registration.py

fixes #1358

Setting the global variable rsb.__defaultParticipantConfig from other modules does not work properly and should probably be avoided altogether.

- examples/protobuf/registration.py: manipulate global default participant config using rsb.setDefaultParticipantConfig() instead of setting rsb.__defaultParticipantConfig directly

Revision 57f8f5b7 - 01/25/2013 03:46 PM - J. Moringen

Backport: Fixed manipulation of default participant config in examples/protobuf/registration.py

refs #1358

Setting the global variable rsb.__defaultParticipantConfig from other modules does not work properly and should probably be avoided altogether.

Revision 1d6edf17 - 01/25/2013 03:47 PM - J. Moringen

Backport: Fixed description of default global participant config in examples-converter.rst

refs #1358

- examples-converter.rst: changed description to reflect that we now use rsb.setDefaultParticipantConfig instead of setting rsb.__defaultParticipantConfig

History

#1 - 01/25/2013 03:40 PM - J. Moringen

- *Status changed from In Progress to Resolved*
- *% Done changed from 0 to 100*

Applied in changeset rsb-python|commit:dd9e64a1bd4b6ba75858fe18df567383d28a92d9.