

Robotics Service Bus - Bug #1410

Python socket transport swallows missing converter errors silently so that clients can end up blocking endlessly

02/13/2013 02:01 PM - J. Wienke

Status:	New	Start date:	02/13/2013
Priority:	Normal	Due date:	
Assignee:		% Done:	0%
Category:	Python	Estimated time:	0.00 hour
Target version:	rsb-0.18		
Description			
<p>The current implementation of the socket transport only defines the following error hook on the connection:</p> <pre>connection.errorHook = lambda exception: self.removeConnection(connection)</pre> <p>This doesn't notify clients in any error case, nor does it print a warning message (without specifically configured logging) or crashes the program.</p> <p>This is the warning code:</p> <pre>self.__logger.warn('Receive error: %s', e)</pre> <p>At least:</p> <ul style="list-style-type: none">- use a more serious warning level- use a method signature that prints a complete exception stacktrace			
Related issues:			
Related to Robotics Service Bus - Tasks # 1036: Implement error handling subs...			In Progress 06/25/2012

History

#1 - 04/17/2013 02:46 PM - J. Moringen

- Target version changed from rsb-0.9 to rsb-0.10

#2 - 12/10/2013 11:47 PM - J. Moringen

- Target version changed from rsb-0.10 to rsb-0.11

#3 - 12/17/2014 03:11 PM - J. Moringen

- Target version changed from rsb-0.11 to rsb-0.12

#4 - 04/30/2015 05:35 PM - J. Moringen

- Target version changed from rsb-0.12 to rsb-0.13

#5 - 03/02/2016 08:55 AM - J. Moringen

- Target version changed from rsb-0.13 to rsb-0.14

#6 - 06/08/2016 09:01 PM - J. Moringen

- Target version changed from rsb-0.14 to rsb-0.15

#7 - 11/07/2016 10:32 AM - J. Moringen

- Target version changed from rsb-0.15 to rsb-0.16

#8 - 04/10/2017 08:59 PM - J. Moringen

- *Target version changed from rsb-0.16 to rsb-0.17*

#9 - 10/10/2017 06:21 PM - J. Moringen

- *Target version changed from rsb-0.17 to rsb-0.18*