

Robotics Service Bus - Bug #1411

TCP_NODELAY missing in python socket transport

02/13/2013 02:15 PM - J. Wienke

Status:	Resolved	Start date:	02/13/2013
Priority:	Normal	Due date:	
Assignee:		% Done:	100%
Category:	Python	Estimated time:	0.00 hour
Target version:	rsb-0.9		
Description			
There is no way to enabled TCP_NODELAY for the python socket transport implementation and it is not set as the default.			

Associated revisions

Revision 0bdce653 - 02/13/2013 05:56 PM - J. Wienke

Implement TCP_NODELAY handling for the socket transport.

fixes #1411

History

#1 - 02/15/2013 09:31 AM - J. Wienke

- Status changed from New to Resolved

- % Done changed from 0 to 100

Applied in changeset rsb-python|commit:0bdce6530a31295cef28fe525e1508a36277f285.