

Robotics Service Bus - Tasks #1414

Document receiving and processing using a thread-safe queue

02/14/2013 02:26 PM - J. Moringen

Status:	New	Start date:	02/14/2013
Priority:	Normal	Due date:	
Assignee:		% Done:	0%
Category:	Documentation	Estimated time:	0.00 hour
Target version:	rsb-0.18		
Description			
For C++, there already is an example program in the rsb-cpp project.			

History

#1 - 03/28/2013 06:13 PM - J. Moringen

- Subject changed from Document reveiving and processing using a thread-safe queue to Document receiving and processing using a thread-safe queue

#2 - 04/17/2013 02:45 PM - J. Wienke

- Target version changed from rsb-0.9 to rsb-0.10

#3 - 12/10/2013 11:47 PM - J. Moringen

- Target version changed from rsb-0.10 to rsb-0.11

#4 - 10/08/2014 08:02 AM - J. Moringen

- Target version changed from rsb-0.11 to rsb-0.12

#5 - 12/17/2014 03:26 PM - J. Moringen

- Blocks deleted (Tasks #1128: Delete wiki pages which duplicate information included in the manual)

#6 - 04/27/2015 11:12 AM - J. Wienke

- Target version changed from rsb-0.12 to rsb-0.13

#7 - 03/02/2016 08:55 AM - J. Moringen

- Target version changed from rsb-0.13 to rsb-0.14

#8 - 04/15/2016 11:31 AM - J. Moringen

- Target version changed from rsb-0.14 to rsb-0.15

#9 - 11/07/2016 10:34 AM - J. Moringen

- Target version changed from rsb-0.15 to rsb-0.16

#10 - 04/10/2017 08:59 PM - J. Moringen

- Target version changed from rsb-0.16 to rsb-0.17

#11 - 10/16/2017 09:23 PM - J. Moringen

- Target version changed from rsb-0.17 to rsb-0.18