

## Robot Control Interface - Tasks #1486

### Check pkgconfig

05/06/2013 05:14 PM - Anonymous

<b>Status:</b> Closed	<b>Start date:</b> 05/06/2013
<b>Priority:</b> High	<b>Due date:</b>
<b>Assignee:</b>	<b>% Done:</b> 0%
<b>Category:</b>	<b>Estimated time:</b> 0.00 hour
<b>Target version:</b> rci0.4	
<b>Description</b>	
cmake configuration is continuously checked on our continuous integration server. also continuously check pkgconfig, ssince this is largely used in AMARSi. See #1443	
<b>Related issues:</b>	
Related to Robotics Systems Commons - Tasks # 1443: Check pkg-config	<b>Resolved</b> <b>02/27/2013</b>

### History

#### #1 - 05/07/2013 06:15 AM - J. Moringen

I did some initial experiments for this in project:rsb (#1448). The problematic aspect is handling of upstream projects (That is the reason why the existing pkg-config test cannot be easily copied from project:rsc, #1443).

I can make my intermediate results available.

#### #2 - 08/12/2013 01:50 PM - Anonymous

- Status changed from New to Closed

Checking pkg-config on our CI server is possible, but handling of upstream dependencies gets a real mess, which doesn't seem to maintainable.

I think the way I will do this is using vagrant to quickly set up a vm with a fresh installation and semi-automatically perform a pkg-config test before release.

#### #3 - 08/12/2013 02:01 PM - Anonymous

- Target version set to rci0.4