

Robotics Service Bus - Feature #1490

Python lacks deserialization support for EventsByScopeMap

05/07/2013 03:15 PM - J. Wienke

Status:	Resolved	Start date:	05/07/2013
Priority:	Normal	Due date:	
Assignee:	J. Wienke	% Done:	100%
Category:	Python	Estimated time:	0.00 hour
Target version:	rsb-0.9		
Description			
There is no converter for this type.			

Associated revisions

Revision 160600fd - 05/08/2013 03:09 PM - J. Wienke

fixes #1490: Implement a converter for EventsByScopeMap.

Merge branch 'feature-1490'

History

#1 - 05/07/2013 03:20 PM - J. Wienke

- % Done changed from 0 to 60

Jan, I have committed something to a respective feature branch. Do you see any problems with this approach?

#2 - 05/07/2013 03:44 PM - J. Moringen

- I think, we decided to use ""..."" for docstrings
- The print statement should be replaced with proper logging or removed
- What does the empty EventsByScopeMap class (line 464) do?
- Why can't serialization be supported?

#3 - 05/07/2013 03:45 PM - J. Moringen

Johannes Wienke wrote:

| *Jan, I have committed something to a respective feature branch. Do you see any problems with this approach?*

Sorry, I read this as "Do you see any problems with this *code*?"

However, third and fourth bullet points remain.

#4 - 05/07/2013 03:47 PM - J. Wienke

Apart from the other things: I don't know how to safely implement serialization because dict is a potentially bad type to use for type matching. This

might lead to so many errors. This is also the reason why I used the internal garbage class so that this converter is not picked up by accident.

#5 - 05/07/2013 04:51 PM - J. Wienke

- % Done changed from 60 to 90

I have committed serialization support and removed the converter from the default registration. Anything else remaining here?

#6 - 05/08/2013 01:47 PM - J. Moringen

- % Done changed from 90 to 60

Looks OK to me.

#7 - 05/08/2013 02:49 PM - J. Wienke

Why only 60%? ;) I will merge it back, if that's ok?

#8 - 05/08/2013 03:00 PM - J. Moringen

Johannes Wienke wrote:

| *Why only 60%? ;)*

I did not change change the progress intentionally. Must have been a missclick or page-reload problem.

| *I will merge it back, if that's ok?*

Sure.

#9 - 05/08/2013 03:20 PM - J. Wienke

- Status changed from *In Progress* to *Resolved*

- % Done changed from 60 to 100

Applied in changeset rsb-python|commit:160600fd72b8dbd2506cbf4490b708706d739b0c.