

Robotics Service Bus - Enhancement #1515

Add data type to all participants, especially listeners

05/27/2013 06:29 PM - J. Wienke

Status:	New	Start date:	05/27/2013
Priority:	Normal	Due date:	
Assignee:		% Done:	0%
Category:	Specification	Estimated time:	0.00 hour
Target version:	rsb-1.0		
Description This would automatically allows to select the correct converter for deserialization. Also, right now the situation is quite seldom that handlers with different data types can work correctly on a single listeners. We should still allow the Any Type for dynamic languages and situations.			
Related issues: Related to Robotics Service Bus - Bug # 515: Data handlers cannot deal with u... <div>New08/19/2011</div>			

History

- #1 - 12/10/2013 11:47 PM - J. Moringen
- Target version changed from rsb-0.10 to rsb-0.11
- #2 - 02/06/2014 05:30 PM - J. Moringen
- Target version changed from rsb-0.11 to rsb-0.12
- #3 - 02/06/2014 05:32 PM - J. Moringen
- Target version changed from rsb-0.12 to rsb-1.0