

Robotics Service Bus - Bug #1517

TCPNODELAY is off by default in C++

05/28/2013 11:34 AM - Anonymous

Status:	Resolved	Start date:	05/28/2013
Priority:	Normal	Due date:	
Assignee:	J. Moringen	% Done:	100%
Category:	C++	Estimated time:	0.00 hour
Target version:	rsb-0.9		
Description			
TCPNODELAY is off by default in C++, although it should be on, right?			
Related issues:			
Related to Robotics Service Bus - Bug # 1518: RSB_TRANSPORT_SOCKET_NODELAY do...		Resolved	05/28/2013

Associated revisions

Revision 7672063f - 05/28/2013 12:52 PM - J. Moringen

Fixed default of transport.socket.tcpnodelay option in src/rsb/transport/*Connector.cpp

fixes #1517

- src/rsb/transport/socket/InPullConnector.cpp (header): updated copyright
(InPullConnector::create): changed default value of "tcpnodelay" option false -> true
- src/rsb/transport/socket/InPushConnector.cpp: likewise
- src/rsb/transport/socket/OutConnector.cpp: likewise

History

#1 - 05/28/2013 11:35 AM - J. Moringen

- Assignee set to J. Moringen

I think so as well. I just didn't get to it yesterday.

#2 - 05/28/2013 01:40 PM - J. Moringen

- Status changed from New to Resolved
- % Done changed from 0 to 100

Applied in changeset rsb-cpp|commit:7672063f86aada6f1056c05599803bd11e30e37f.