# Robotics Service Bus - Bug #1517 TCPNODELAY is off by default in C++

05/28/2013 11:34 AM - Anonymous

Status: Resolved Start date: 05/28/2013

Priority: Normal Due date:

Assignee:J. Moringen% Done:100%Category:C++Estimated time:0.00 hour

Target version: rsb-0.9

Description

TCPNODELAY is off by default in C++, although it should be on, right?

Related issues:

Related to Robotics Service Bus - Bug # 1518: RSB\_TRANSPORT\_SOCKET\_NODELAY do... Resolved 05/28/2013

#### **Associated revisions**

# Revision 7672063f - 05/28/2013 12:52 PM - J. Moringen

Fixed default of transport.socket.tcpnodelay option in src/rsb/transport/\*Connector.cpp

fixes #1517

 $- \ src/rsb/transport/socket/InPullConnector.cpp \ (header): updated$ 

copyright

(InPullConnector::create): changed default value of "tcpnodelay"

option false -> true

- src/rsb/transport/socket/InPushConnector.cpp: likewise
- src/rsb/transport/socket/OutConnector.cpp: likewise

### History

#### #1 - 05/28/2013 11:35 AM - J. Moringen

- Assignee set to J. Moringen

I think so as well. I just didn't get to it yesterday.

### #2 - 05/28/2013 01:40 PM - J. Moringen

- Status changed from New to Resolved
- % Done changed from 0 to 100

Applied in changeset rsb-cpp|commit:7672063f86aada6f1056c05599803bd11e30e37f.

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