

Robotics Service Bus - Bug #1518

RSB_TRANSPORT_SOCKET_NODELAY documentation seems erroneous

05/28/2013 11:51 AM - Anonymous

Status:	Resolved	Start date:	05/28/2013
Priority:	Normal	Due date:	
Assignee:	J. Moringen	% Done:	100%
Category:	Documentation	Estimated time:	0.00 hour
Target version:	rsb-0.9		
Description			
<p>In the RSB manual, tcp_nodelay for the socket transport is documented to be set through the environment variable RSB_TRANSPORT_SOCKET_NODELAY, where in fact it is RSB_TRANSPORT_SOCKET_TCPNODELAY (at least for c++).</p> <p>This might be pointing to an inconsistency between the different language implementations (it seems to be just nodelay instead of tcpnodelay in CL, although I'm not an expert in reading CL code).</p>			
Related issues:			
Related to Robotics Service Bus - Bug # 1517: TCPNODELAY is off by default in...		Resolved	05/28/2013
Related to Robotics Service Bus - Bug # 1519: Option for controlling TCP_NODE...		Resolved	05/28/2013

Associated revisions

Revision c0f78250 - 05/28/2013 12:51 PM - J. Moringen

Fixed RSB_TRANSPORT_SOCKET_{NODELAY -> TCPNODELAY} in common.rst

fixes #1518

- common.rst: fixed name of environment variable RSB_TRANSPORT_SOCKET_{NODELAY -> TCPNODELAY} to match description in specification-socket.rst and implementations

History

#1 - 05/28/2013 12:47 PM - Anonymous

Forgot to paste the link:

<http://docs.cor-lab.org/rsb-manual/trunk/html/common.html>

#2 - 05/28/2013 01:04 PM - J. Moringen

- Status changed from Feedback to Resolved
- % Done changed from 0 to 100

Applied in changeset rsb-manual|commit:c0f78250c62c74c96a7271043b0b617760af65b6.