# Robotics Service Bus - Enhancement #1549
# The documentation should mention that one Spread daemon is usually enough

06/25/2013 01:59 PM - J. Moringen

| | | | | |
|---|---|---|---|---|
| **Status:** | Resolved | | **Start date:** | 06/25/2013 |
| **Priority:** | Normal | | **Due date:** | |
| **Assignee:** | J. Moringen | | **% Done:** | 100% |
| **Category:** | Documentation | | **Estimated time:** | 0.00 hour |
| **Target version:** | rsb-0.9 | | | |

**Description**

In many case, including distribution over multiple machines, a single Spread daemon is enough. In addition, configuring multiple Spread daemons correctly is not easy and lead to severe network problems.

The documentation should discuss these issues.

**Associated revisions**

**Revision aacfc2f2 - 07/14/2013 08:57 PM - J. Moringen**

Added "How many Spread Daemons do I need?" in troubleshooting.rst

fixes #1549

- troubleshooting.rst (How many Spread Daemons do I need?): new entry;
   explain potential problems and tradeoffs of running Spread daemons

**History**

**#1 - 07/14/2013 08:56 PM - J. Moringen**

*- Status changed from New to In Progress*

*- Assignee set to J. Moringen*

**#2 - 07/14/2013 11:25 PM - J. Moringen**

*- Status changed from In Progress to Resolved*

*- % Done changed from 0 to 100*

Applied in changeset rsb-manual|commit:aacfc2f29831d4854570171b7a32bb5ad3592216.