Robotics Service Bus - Enhancement #1551 Improve documentation of socket transport's "auto" mode

06/25/2013 02:04 PM - J. Moringen

Status: Resolved Start date: 06/25/2013

Priority: Due date: Normal

Assignee:

% Done: 100%

Estimated time: Category: Documentation 0.00 hour Target version: rsb-0.9

Description

For example, mention that mode = auto and nothing else cannot work across multiple machines.

Related issues:

Related to Robotics Service Bus - Enhancement # 1550: "Auto" mode of the sock... New 06/25/2013

Associated revisions

Revision e0358e63 - 07/14/2013 12:18 AM - J. Moringen

Improved documentation of socket transport's "auto" mode

fixes #1551

- common.rst (RSB_TRANSPORT_SOCKET_SERVER): added a warning stating that the "auto" mode only works properly on single computer
- specification-socket.rst (Addresses and Ports): added an explanation of why the "auto" mode only works properly on a single computer
- troubleshooting.rst (Configuring the TCP-based Transport): added a reference to RSB_TRANSPORT_SOCKET_SERVER (I cannot make the Socket Transport with "auto" Mode work across multiple Machines): new item; explain why the socket transport's "auto" mode usually does not work across multiple computers; suggest using the Spread transport and explain how to setup the socket transport without "auto" mode

History

#1 - 07/14/2013 12:35 AM - J. Moringen

- Status changed from New to Resolved
- % Done changed from 0 to 100

Applied in changeset rsb-manual|commit:e0358e637d4c060a8e92f2759848cf3d58ffb457.

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