Robotics Service Bus - Enhancement #1551
Improve documentation of socket transport's "auto" mode

06/25/2013 02:04 PM - J. Moringen

Status:	Resolved		**Start date:**	06/25/2013
Priority:	Normal		**Due date:**	
Assignee:			**% Done:**	100%
Category:	Documentation		**Estimated time:**	0.00 hour
Target version:	rsb-0.9			

Description

For example, mention that mode = auto and nothing else cannot work across multiple machines.

Related issues:		
Related to Robotics Service Bus - Enhancement # 1550: "Auto" mode of the sock...	**New**	**06/25/2013**

Associated revisions

Revision e0358e63 - 07/14/2013 12:18 AM - J. Moringen

Improved documentation of socket transport's "auto" mode

fixes #1551

- common.rst (RSB_TRANSPORT_SOCKET_SERVER): added a warning stating
  that the "auto" mode only works properly on single computer
- specification-socket.rst (Addresses and Ports): added an explanation
  of why the "auto" mode only works properly on a single computer
- troubleshooting.rst (Configuring the TCP-based Transport): added a
  reference to RSB_TRANSPORT_SOCKET_SERVER
  (I cannot make the Socket Transport with "auto" Mode work across multiple Machines):
  new item; explain why the socket transport's "auto" mode usually
  does not work across multiple computers; suggest using the Spread
  transport and explain how to setup the socket transport without
  "auto" mode

History

#1 - 07/14/2013 12:35 AM - J. Moringen

- *Status changed from New to Resolved*
- *% Done changed from 0 to 100*

Applied in changeset rsb-manual|commit:e0358e637d4c060a8e92f2759848cf3d58ffb457.