

Robotics Service Bus - Feature #1657

Improve exception messages for failed connector construction

11/14/2013 09:37 AM - J. Moringen

Status:	Resolved	Start date:	11/14/2013
Priority:	Normal	Due date:	
Assignee:	J. Moringen	% Done:	100%
Category:	C++	Estimated time:	0.00 hour
Target version:	rsb-0.10		
Description			
The exception messages should at least include the transport name and the direction.			
See e.g. https://projects.cor-lab.de/issues/1942 for a case in which this information would have been helpful.			
Related issues:			
Related to Robotics Service Bus - Enhancement # 1658: Do not require converte...		Resolved	11/15/2013

Associated revisions

Revision eefd885a - 11/14/2013 10:11 AM - J. Moringen

Improved exception messages in create*Connectors in src/rsb/Factory.cpp

fixes #1657

- src/rsb/Factory.cpp (Factory::createInPullConnectors): include transport name and direction in exception message
- (Factory::createInPushConnectors): likewise
- (Factory::createOutConnectors): likewise

Revision 4364cbc6 - 11/14/2013 11:28 AM - J. Moringen

Backport: Improved exception messages in create*Connectors in src/rsb/Factory.cpp

refs #1657

- src/rsb/Factory.cpp (Factory::createInPullConnectors): include transport name and direction in exception message
- (Factory::createInPushConnectors): likewise
- (Factory::createOutConnectors): likewise

History

#1 - 11/14/2013 10:12 AM - J. Moringen

- Status changed from *In Progress* to *Resolved*
- % Done changed from 0 to 100

Applied in changeset rsb-cpp|commit:eefd885a62d75312d199e1231a05965d26a75817.