

Robotics Systems Types - Feature #1792

Add LaserScan to sandbox

03/06/2014 03:59 PM - L. Ziegler

Status:	Resolved	Start date:	03/06/2014
Priority:	Normal	Due date:	
Assignee:		% Done:	100%
Category:	Type Proposal	Estimated time:	0.00 hour
Target version:			
Description			
Please add the type to the 0.10 sandbox.			

Associated revisions

Revision d2f4f61c - 04/22/2014 05:46 PM - L. Ziegler

Added new type LaserScan in proto/sandbox/rst/vision/LaserScan.proto

refs #1792

- proto/sandbox/rst/vision/LaserScan.proto: new file; type for laser scans

Signed-off-by: Jan Moringen <jmoringe@techfak.uni-bielefeld.de>

Revision b5de0c0f - 04/22/2014 05:47 PM - L. Ziegler

Backport: Added new type LaserScan in proto/sandbox/rst/vision/LaserScan.proto

fixes #1792

- proto/sandbox/rst/vision/LaserScan.proto: new file; type for laser scans

Signed-off-by: Jan Moringen <jmoringe@techfak.uni-bielefeld.de>

History

#1 - 04/22/2014 04:42 PM - L. Ziegler

Progress on this would be appreciated.

#2 - 04/22/2014 05:48 PM - L. Ziegler

- Status changed from New to Resolved
- % Done changed from 0 to 100

Applied in changeset rst-[proto|commit:b5de0c0fe1b899fe083b8bbc6147cdf342207417](https://code-review.ros.org/commit/b5de0c0fe1b899fe083b8bbc6147cdf342207417).

Files

0003-added-new-type-LaserScan.patch

1.35 KB

03/06/2014

L. Ziegler