

Robotics Systems Types - Feature #1802

Change type Translation

03/13/2014 04:55 PM - L. Ziegler

Status: Resolved	Start date: 03/13/2014
Priority: Normal	Due date:
Assignee:	% Done: 100%
Category: Type Proposal	Estimated time: 0.00 hour
Target version:	
Description	
Add field for coordinate frame id to Translation.	

Associated revisions

Revision c4c8fa32 - 04/14/2014 07:32 PM - L. Ziegler

Added field for frame id to type Translation

fixes #1802

History

#1 - 04/14/2014 07:33 PM - L. Ziegler

- Status changed from New to Resolved

- % Done changed from 0 to 100

Applied in changeset rst-protolcommit:c4c8fa32c946429fd354eea65854ba708ca2d32a.

Files

0009-Added-field-for-frame-id-to-type-Translation.patch	780 Bytes	03/13/2014	L. Ziegler
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