

Robotics Systems Types - Feature #1803

Change type Rotation

03/13/2014 04:55 PM - L. Ziegler

Status:	Resolved	Start date:	03/13/2014
Priority:	Normal	Due date:	
Assignee:		% Done:	100%
Category:	Type Proposal	Estimated time:	0.00 hour
Target version:			
Description			
Add field for coordinate frame id to Rotation.			

Associated revisions

Revision 0cde2407 - 04/14/2014 07:32 PM - L. Ziegler

Added field for frame id to type Rotation

fixes #1803

History

#1 - 04/14/2014 07:40 PM - L. Ziegler

- Status changed from New to Resolved

- % Done changed from 0 to 100

Applied in changeset rst-proto|commit:0cde2407419100f9726ac0f9e32133e1b42b720f.

Files

0010-Added-field-for-frame-id-to-type-Rotation.patch

750 Bytes

03/13/2014

L. Ziegler