

## Robotics Service Bus - Feature #1870

### Allow (optional) parallel method calls

05/08/2014 02:36 PM - J. Moringen

<b>Status:</b>	New	<b>Start date:</b>	05/08/2014
<b>Priority:</b>	Normal	<b>Due date:</b>	
<b>Assignee:</b>		<b>% Done:</b>	0%
<b>Category:</b>		<b>Estimated time:</b>	0.00 hour
<b>Target version:</b>			
<b>Description</b>			
- Johannes will commit patches containing a short-term workaround for C++ and Java			

#### Associated revisions

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##### Revision 19adc75a - 05/08/2014 05:03 PM - J. Wienke

Add parallel call parameter to ParallelEventReceivingStrategy

Adds a config option to ParallelEventReceivingStrategy that allows to specify whether individual handlers might be called in parallel with potentially overlapping calls. This might result in situations that conflict with the specified QoS-settings because if the new parameter is set to true, dispatched events might appear out of order to the client code due to thread scheduling issues.

refs #1870

#### History

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##### #1 - 05/08/2014 05:06 PM - J. Wienke

The temporary patches I proposed with Leon are applied now in the master version.

##### #2 - 06/30/2016 12:36 PM - J. Wienke

- Assignee deleted (J. Wienke)