Robotics Service Bus - Bug #1896
Documentation of cpp-spread-plugin missing?

06/12/2014 10:54 AM - Anonymous

Status:	Resolved		**Start date:**	06/12/2014
Priority:	Normal		**Due date:**	
Assignee:	J. Wienke		**% Done:**	100%
Category:	Documentation		**Estimated time:**	0.00 hour
Target version:	rsb-0.11			

Description

The C++ Implementation docu documents how to build rsb and how to build spread, but doesn't seem to mention that one needs to build the spread plugin in order to use it with rsb.

Associated revisions

Revision 57439e13 - 12/17/2014 11:37 AM - J. Wienke

Explain from-source installation of spread plugin

Include the spread plugin in the compilation instructions.

fixes #1896

History

#1 - 12/17/2014 11:14 AM - J. Wienke

- Status changed from New to In Progress

- Assignee set to J. Wienke

#2 - 12/17/2014 11:40 AM - J. Wienke

- Status changed from In Progress to Resolved

- % Done changed from 0 to 100

Applied in changeset commit:rsb-manual|57439e13ee05a9e22dab378f1e25cdd4bc72b89c.