

## Robotics Service Bus - Bug #191

### Python spread blocks at least sigint

02/15/2011 05:56 PM - I. Lütkebohle

<b>Status:</b>	Rejected	<b>Start date:</b>	02/15/2011
<b>Priority:</b>	Normal	<b>Due date:</b>	
<b>Assignee:</b>		<b>% Done:</b>	0%
<b>Category:</b>	Python	<b>Estimated time:</b>	0.00 hour
<b>Target version:</b>	rsb-0.7		
<b>Description</b>			
Programme die RSBPython verwenden reagieren nicht mehr auf Ctrl-C.			
<b>Related issues:</b>			
Related to RSB Component Testing Framework - Bug # 981: Timeout not working w...			<b>Closed</b> <b>04/13/2012</b>

#### History

##### #1 - 04/08/2011 05:07 PM - J. Wienke

- Category set to Python

##### #2 - 05/25/2011 07:02 PM - J. Moringen

This might be caused by Spread interacting with signal handlers: The same behavior regarding SIGINT can be observed when using libspread from Lisp.

##### #3 - 09/01/2011 06:56 PM - J. Wienke

- % Done changed from 0 to 10

Somehow it is possible to kill every rsb-python based software with ctrl+4. Why? ;)

##### #4 - 06/22/2012 03:50 PM - J. Wienke

- Subject changed from Ctrl-C für RSBPython to Python spread blocks at least sigint

- Status changed from New to Rejected

- Target version set to rsb-0.7

- % Done changed from 10 to 0

This is a problem of the C implementation of spread. This blocks at least sigint, which consequently prevents the receiving thread from handling this signal. So we cannot do much about this.