

Robotics Systems Types - Tasks #1912

Add joint velocities type

07/03/2014 05:26 PM - Anonymous

Status: Resolved	Start date: 07/03/2014
Priority: Normal	Due date:
Assignee:	% Done: 100%
Category: Type Proposal	Estimated time: 0.00 hour
Target version:	
Description Ass joint velocities type corresponding to joint angles type. Should be - repeated float with SI unit rad/s	
Related issues:	
Related to Robotics Systems Types - Tasks # 2005: Backport joint velocities t...	Closed 09/16/2014
Blocks Robotics Systems Types - Tasks # 1910: Add rci rst converter for Joint...	Resolved 06/30/2014

Associated revisions

Revision 0c46e055 - 07/04/2014 10:06 AM - Arne Nordmann

Added joint velocities type to rst dynamics sandbox

- Repeated field of angular velocities of multiple joints in rad/s

refs #1912

History

#1 - 07/04/2014 10:15 AM - Anonymous

- File 0001-Added-joint-velocities-type-to-rst-dynamics-sandbox.patch added

#2 - 07/04/2014 10:25 AM - Anonymous

- Blocks Tasks #1910: Add rci rst converter for Joint Velocities added

#3 - 07/04/2014 10:26 AM - Anonymous

- Status changed from New to Resolved

- % Done changed from 0 to 100

#4 - 07/04/2014 10:48 AM - Anonymous

Moved to rst.kinematics package, see #1913

#5 - 09/16/2014 02:55 PM - Anonymous

- Related to Tasks #2005: Backport joint velocities type to 0.9 added

Files

0001-Added-joint-velocities-type-to-rst-dynamics-sandbox.patch	1.1 KB	07/04/2014	Anonymous
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