

## Robotics Service Bus - Feature #194

### Get ID from published data

02/17/2011 02:59 PM - I. Lütkebohle

<b>Status:</b>	Resolved	<b>Start date:</b>	02/17/2011
<b>Priority:</b>	Normal	<b>Due date:</b>	
<b>Assignee:</b>		<b>% Done:</b>	100%
<b>Category:</b>	C++	<b>Estimated time:</b>	0.00 hour
<b>Target version:</b>	0.2		
<b>Description</b>			
Essentially, return the RSBEvent from publishData.			
<b>Related issues:</b>			
Duplicated by Robotics Service Bus - Feature # 207: Publish operation should ...		<b>Rejected</b>	<b>02/22/2011</b>

#### Associated revisions

##### Revision 8a9e478e - 05/16/2011 04:49 PM - J. Moringen

Method publish returns created event in src/rsb/Informer.h

fixes #194

- src/rsb/Informer.h: all Informer::publish methods return the event after sending
- test/rsb/UserLevelTest.cpp: added test case to check returned events; renamed test suite PublisherTest -> InformerTest

#### History

##### #1 - 04/29/2011 05:54 PM - J. Wienke

What is the use case for this?

##### #2 - 04/29/2011 05:56 PM - I. Lütkebohle

When referencing an event, I need an id, which is created when RSBEvent is instantiated. publishData creates the RSBEvent internally, so I can't get the id. Returning the event from publishData would provide this, and more.

##### #3 - 05/16/2011 02:33 PM - J. Wienke

- Category set to C++
- Target version set to 0.2

##### #4 - 05/16/2011 04:49 PM - J. Moringen

- Status changed from New to Resolved
- % Done changed from 0 to 100

Applied in changeset r846.