Robotics Systems Types - Tasks #2005
Backport joint velocities type to 0.9

09/16/2014 02:55 PM - Anonymous

Status:	Closed		**Start date:**	09/16/2014
Priority:	Normal		**Due date:**	
Assignee:			**% Done:**	0%
Category:	Type Proposal		**Estimated time:**	0.00 hour
Target version:	rsb-0.9			

Description

Related issues:		
Related to Robotics Systems Types - Tasks # 1912: Add joint velocities type	**Resolved**	**07/03/2014**

History

#1 - 09/16/2014 02:55 PM - Anonymous

- Related to Tasks #1912: Add joint velocities type added

#2 - 01/06/2015 06:01 PM - J. Moringen

Is this still needed?

#3 - 01/08/2015 01:56 PM - Anonymous

- Status changed from New to Closed

I don't think so. I put the relevant users in cc and close the issue. Please re-open, if this is still an issue.