

Robotics Service Bus - Tasks #2011

Update examples and documentation to use `rsc::misc::{waitForSignal,lastArrivedSignal}`

09/19/2014 02:56 PM - J. Moringen

Status:	Resolved	Start date:	09/19/2014
Priority:	High	Due date:	
Assignee:	J. Moringen	% Done:	100%
Category:	Documentation	Estimated time:	0.00 hour
Target version:	rsb-0.11		
Description			
Related issues:			
Related to Robotics Systems Commons - Feature # 2007: Provide a mechanism for...		Resolved	09/16/2014

Associated revisions

Revision a3512117 - 09/19/2014 02:57 PM - J. Moringen

Use `rsc::misc::{waitForSignal,hasSignalArrived}` in `examples/**/*.cpp`

refs #2011

- `examples/inter_transport/inprocess-and-socket.cpp` (header): updated copyright
(main): use `rsc::misc::waitForSignal`
- `examples/inter_transport/socket-only.cpp` (header): updated copyright
(main): use `rsc::misc::waitForSignal`
- `examples/listener/listener.cpp` (header): updated copyright
(main): use `rsc::misc::waitForSignal`
- `examples/listener/receiveFile.cpp` (main): likewise
- `examples/meta_data/receiver.cpp` (header): updated copyright
(main): use `rsc::misc::waitForSignal`
- `examples/protobuf_converter/receiver.cpp` (header): updated copyright
(main): use `rsc::misc::waitForSignal`
- `examples/queue_processing/queueprocessing.cpp` (main): use `rsc::misc::hasSignalArrived`
- `examples/reader/reader.cpp` (header): updated copyright
(main): use `rsc::misc::hasSignalArrived`
- `examples/rosetta_converter/receiver.cpp` (header): updated copyright
(main): use `rsc::misc::waitForSignal`

Revision a7e2fffc - 12/17/2014 03:06 PM - J. Moringen

Use RSC `SignalWaiter` mechanism in `examples/**/*.cpp`

fixes #2011

- `examples/queue_processing/queueprocessing.cpp`: use `SignalWaiter` for waiting and return value
- `examples/reader/reader.cpp`: likewise
- `examples/server/server.cpp`: likewise
- `examples/timed_informer/informer.cpp`: likewise

History

#1 - 09/19/2014 05:06 PM - J. Moringen

- % Done changed from 0 to 50

#2 - 09/19/2014 05:08 PM - J. Moringen

- Related to Feature #2007: Provide a mechanism for waiting until a termination request (e.g. SIGINT) arrives added

#3 - 09/24/2014 08:27 PM - J. Moringen

- Subject changed from Update examples and documentation to use `rsc::misc::{waitForSignal,hasSignalArrived}` to Update examples and documentation to use `rsc::misc::{waitForSignal,lastArrivedSignal}`

#4 - 09/24/2014 09:12 PM - J. Wienke

Actually I already fixed compilation for some of the binaries after the API change. I probably forgot to add this issue as a reference.

#5 - 11/27/2014 01:19 PM - S. Wrede

- Priority changed from Normal to High

#6 - 12/17/2014 11:14 AM - J. Wienke

Does anyone remember what is still missing here?

#7 - 12/17/2014 03:08 PM - J. Moringen

- Status changed from In Progress to Resolved

- % Done changed from 50 to 100

Applied in changeset commit:rsb-cpp|a7e2ffcadef545e9090571cf792e321ff015296.