

## Robotics Service Bus - Bug #2032

### rsb-loggercpp0.11 invocation error

09/29/2014 05:08 PM - T. Korthals

<b>Status:</b>	Resolved	<b>Start date:</b>	09/29/2014
<b>Priority:</b>	High	<b>Due date:</b>	
<b>Assignee:</b>	J. Wienke	<b>% Done:</b>	100%
<b>Category:</b>	Packaging	<b>Estimated time:</b>	0.00 hour
<b>Target version:</b>	rsb-0.11		

#### Description

##### Platform

Ubuntu Trusty on x86 (virtual Box & **fresh install**)

##### Programs and Programming Languages

C++

##### RSB Version

installed Debian packages (<http://docs.cor-lab.de//rsb-manual/trunk/html/install-binary.html#debian-packages>)

##### What did you do?

invoke rsb-loggercpp0.11

##### What did you expect to happen?

Normal execution

##### What happened instead?

```
$ rsb-loggercpp0.11 / --style detailed
```

```
rsb-loggercpp0.11: symbol lookup error: rsb-loggercpp0.11: undefined symbol:
```

```
_ZN3rsb7Factory14createListenerERKNS_5ScopeERKNS_17ParticipantConfigEN5boost10shared_ptrINS_11ParticipantEEE
```

##### Additional information

Your tutorials do compile and run just fine

#### History

##### #1 - 09/29/2014 05:35 PM - J. Wienke

- Category changed from C++ Tools to Packaging
- Status changed from New to Resolved
- Assignee changed from J. Moringen to J. Wienke
- % Done changed from 0 to 100

It seems the CI-server configuration broke at some point in time and hence the debian package for RSB wasn't rebuilt since a long time. A new rsb package should appear soon on the server. After updating your installation, things should work again.