Robotics Service Bus - Feature #207
Publish operation should return RSBEvent

02/22/2011 09:53 PM - S. Wrede

Status:	Rejected		**Start date:**	02/22/2011
Priority:	Normal		**Due date:**	
Assignee:			**% Done:**	0%
Category:	C++		**Estimated time:**	0.00 hour
Target version:				

Description

Calls to ::publish on informers shall return the RSBEvent to the user for further processing. For instance, if access to an internally generated event id is needed or some other kind of framework-generated metadata.

Related issues:

Duplicates Robotics Service Bus - Feature # 194: Get ID from published data	**Resolved**	**02/17/2011**

History

#1 - 02/22/2011 09:55 PM - S. Wrede

Exemplified in the RSBJava::Publisher class where send<T> and send(RSBEvent) both return the modified Event to the user.

#2 - 04/08/2011 05:07 PM - J. Wienke

- Category set to C++

#3 - 04/29/2011 06:00 PM - J. Wienke

- Status changed from New to Rejected