

Robotics Service Bus - Bug #2080

spread connect error

11/09/2014 10:42 AM - Q. Li

<b>Status:</b>	Closed	<b>Start date:</b>	11/09/2014
<b>Priority:</b>	Normal	<b>Due date:</b>	
<b>Assignee:</b>	Q. Li	<b>% Done:</b>	0%
<b>Category:</b>	Spread Connector	<b>Estimated time:</b>	0.00 hour
<b>Target version:</b>	rsb-0.11		
<b>Description</b>			
<p>I am using RSB for two computer(kuka-vision and kuka-arm) communication.</p> <p>The communication can be constructed, but after a short time running, programe running in kuka-vision complain the following error.</p> <p>in both computer I am using rsb.conf</p> <pre>[transport.spread] enabled = 1 host = kuka-arm</pre> <p>SP_error: (-1) Illegal spread was provided</p> <p>1415524406281 rsb.transport.spread.spreadconnection [FATAL]: Error connecting to '4803@kuka-arm': connection to spread daemon at 4803@kuka-arm failed, check port and hostname</p> <p>terminate called after throwing an instance of 'rsb::CommException'</p> <p>what(): Error connecting to '4803@kuka-arm': connection to spread daemon at 4803@kuka-arm failed, check port and hostname</p> <p>Aborted</p>			

History

#1 - 11/10/2014 01:46 PM - J. Moringen

- Category set to Spread Connector
- Status changed from New to Feedback
- Assignee changed from J. Moringen to Q. Li
- Target version set to rsb-0.11

Thanks for the report. Unfortunately, it does not contain enough information to diagnose the problem. Please provide a more detailed description according to the [guidelines in the manual](#).

I can still say that something seems wrong:

```
SP_error: (-1) Illegal spread was provided
1415524406281 rsb.transport.spread.spreadconnection [FATAL]: Error connecting to '4803@kuka-arm': connection to spread daemon at
4803@kuka-arm failed, check port and hostname
terminate called after throwing an instance of 'rsb::CommException'
what(): Error connecting to '4803@kuka-arm': connection to spread daemon at 4803@kuka-arm failed, check port and hostname
Aborted
```

This should only happen when initially connecting to the Spread daemon. Does your program create and destroy RSB informers and/or listeners while it runs?

#2 - 11/10/2014 03:08 PM - Q. Li

Thanks, Jan.

I find the problem. I am creating/destroy the informer during its running. My problem is solved.

**#3 - 11/10/2014 03:17 PM - J. Moringen**

- *Status changed from Feedback to Closed*