

Robotics Service Bus - Feature #2170

Visual indication when rsb-logger* (or any other rsb-tool) is ready

02/09/2015 05:58 PM - N. Köster

Status:	New	Start date:	02/09/2015
Priority:	Low	Due date:	
Assignee:	J. Moringen	% Done:	0%
Category:	Common Lisp Tools	Estimated time:	0.00 hour
Target version:	rsb-0.18		

Description

When providing/loading multiple idl path(s)/files(s), the logger may take some time to load (as described [here](#) and as expected).

Example:

```
rsb-loggercl --idl-path="/vol/csra/releases/trusty/lsp-csra-nightly/share/rst0.11/proto/stable/" \  
  --idl-path="/vol/csra/releases/trusty/lsp-csra-nightly/share/rst0.11/proto/sandbox" \  
  --load-idl="/vol/csra/releases/trusty/lsp-csra-nightly/share/rst0.11/proto/**/* .proto" \  
  --style=detailed \  
  /rsbopencv/persons/
```

However, (for usability reasons) it would be nice to get a visual indication/feedback (e.g. simple print saying **ready**) to know if the logger is ready. This is important when using rsb with socket communication, as the order of launching components is important here.

History

#1 - 02/10/2015 01:00 PM - J. Moringen

- Target version set to rsb-0.12

#2 - 08/19/2015 04:15 PM - J. Wienke

- Target version changed from rsb-0.12 to rsb-0.13

#3 - 03/02/2016 08:55 AM - J. Moringen

- Target version changed from rsb-0.13 to rsb-0.14

#4 - 06/08/2016 09:01 PM - J. Moringen

- Target version changed from rsb-0.14 to rsb-0.15

#5 - 11/07/2016 10:33 AM - J. Moringen

- Target version changed from rsb-0.15 to rsb-0.16

#6 - 04/10/2017 08:59 PM - J. Moringen

- Target version changed from rsb-0.16 to rsb-0.17

#7 - 10/16/2017 09:23 PM - J. Moringen

- Target version changed from rsb-0.17 to rsb-0.18