Robotics Service Bus - Bug #2194 Spread connection are not properly disconnected

03/09/2015 07:30 PM - J. Wienke

Status:	Resolved	Start date:	03/09/2015	
Priority:	Urgent	Due date:		
Assignee:	J. Wienke	% Done:	100%	
Category:	Spread Connector	Estimated time:	0.00 hour	
Target version:	rsb-0.11			
Description				
There is no call to SI	P_disconnect in the cpp spread cod	e at all.		

Associated revisions

Revision 0c5293c1 - 03/10/2015 10:28 AM - J. Wienke

Properly close spread connections

Somehow this never happened and no one noticed so far.

fixes #2194

Revision 4b3c7f34 - 03/10/2015 10:29 AM - J. Wienke

Properly close spread connections

Somehow this never happened and no one noticed so far.

fixes #2194

(cherry picked from commit 0c5293c150a080ab1e30f38a08fad7b65d010ca3)

History

#1 - 03/10/2015 10:29 AM - J. Wienke

- Status changed from New to In Progress
- Assignee set to J. Wienke

#2 - 03/10/2015 10:29 AM - J. Wienke

- Status changed from In Progress to Resolved
- % Done changed from 0 to 100

Applied in changeset commit:rsb-spread-cpp|0c5293c150a080ab1e30f38a08fad7b65d010ca3.