Robotics Service Bus - Bug #2194
Spread connection are not properly disconnected

03/09/2015 07:30 PM - J. Wienke

Status:	Resolved		**Start date:**	03/09/2015
Priority:	Urgent		**Due date:**	
Assignee:	J. Wienke		**% Done:**	100%
Category:	Spread Connector		**Estimated time:**	0.00 hour
Target version:	rsb-0.11			

Description

There is no call to SP_disconnect in the cpp spread code at all.

Associated revisions

Revision 0c5293c1 - 03/10/2015 10:28 AM - J. Wienke

Properly close spread connections

Somehow this never happened and no one noticed so far.

fixes #2194

Revision 4b3c7f34 - 03/10/2015 10:29 AM - J. Wienke

Properly close spread connections

Somehow this never happened and no one noticed so far.

fixes #2194

(cherry picked from commit 0c5293c150a080ab1e30f38a08fad7b65d010ca3)

History

#1 - 03/10/2015 10:29 AM - J. Wienke

- Status changed from New to In Progress

- Assignee set to J. Wienke

#2 - 03/10/2015 10:29 AM - J. Wienke

- Status changed from In Progress to Resolved

- % Done changed from 0 to 100

Applied in changeset commit:rsb-spread-cpp|0c5293c150a080ab1e30f38a08fad7b65d010ca3.